

**SUBJECT CODE NO:- P-97**  
**FACULTY OF ENGINEERING AND TECHNOLOGY**  
**T.E.(EEP/EE/EEE) Examination May/June 2017**  
**Microprocessor & Interfacing**  
**(Revised)**

[Time: Three Hours]

[Max.Marks:80]

Please check whether you have got the right question paper.

- N.B
- i) Q.No.1 and Q.No.6 are compulsory.
  - ii) Attempt any two questions from the remaining questions in each section
  - iii) assume suitable data & addresses if necessary
  - iv) Figure to the right indicates full marks.

Section A

Q.1	Solve any five	10
	<ol style="list-style-type: none"><li>1) What is microprocessor?</li><li>2) Explain function of instruction register</li><li>3) Why program counter and stack pointer are 16 bit registers?</li><li>4) What is opcode &amp; operand</li><li>5) How many T-states are required for opcode fetch &amp; memory read operation</li><li>6) What is function of <math>\overline{RD}</math> &amp; <math>\overline{WR}</math> control signals</li><li>7) Give functional categories of 8085 instructions</li><li>8) What happens when STA C200H instruction executed</li></ol>	
Q.2	a) Explain addressing modes of 8085	08
	b) Draw the interrupt structure of 8085 and explain in brief	07
Q.3	a) Draw and explain brief the flag register of 8085	08
	b) Explain in detail CALL & RET instructions	07
Q.4	a) Some numbers are stored from memory location D201H . Count of the number is stored at D200H. Write 8085 ALP to find largest number and store the result at C200 H . Handrun the program.	08
	b) Explain in detail Architecture of 8085	07
Q.5	Write short notes on ( Any three)	15
	<ol style="list-style-type: none"><li>1) Stack and subroutines</li><li>2) Concept of looping</li><li>3) Features of Intel 8085</li><li>4) Functions of SID &amp; SOD pin</li></ol>	

Section B

- Q.6 Solve any five 10
- 1) What happens when following instructions are executed
    - a) IN P<sub>A</sub> b) OUT P<sub>B</sub>
  - 2) What is use of 8253 PIT
  - 3) Enlist different I/O modes of 8255
  - 4) Write O/P control word of 8255 in simple I/O mode all port O/P port
  - 5) What is use of USART
  - 6) Write output control signals used in 8259 A
  - 7) Explain function of SID & SOD pin
  - 8) What is ADC & DAC ?
- Q.7 10
- a) Explain in brief mode 0 and mode 1 of 8255
  - b) Write an 8085 ALP to output the data 22H, 33H, 44H, on port A, port B and Port C of 8255 05  
respectively address of port A is 80H
- Q.8 07
- a) Explain block diagram of 8259 A
  - b) An 8253 is connected to 1 MHz clock it is used to generate a square signal of 1 Hz frequency 08  
give interfacing circuit & program to achieve 8085 based  $\mu$ p system assume address of counter O is 40H
- Q.9 08
- a) Explain the block diagram of 8279 08
  - b) Draw the interfacing diagram of stepper motor and write ALP to rotate in clockwise direction 07  
Assume delay subroutine is available at "DELAY"
- Q.10 Write short notes ( any three) 15
- 1) DC motor speed control
  - 2) Measurement of frequency using 8085
  - 3) Mode 0 of 8253
  - 4) 8051 USART

**'Appendix A'**

**Programmable communication interface 8251 A :**

(i) **A synchronous mode format :**

S <sub>2</sub>	S <sub>1</sub>	EP	PEN	L <sub>2</sub>	L <sub>1</sub>	B <sub>2</sub>	B <sub>1</sub>
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(ii) **Synchronous mode format :**

SCS	ESD	EP	PEN	L <sub>2</sub>	L <sub>1</sub>	0	0
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(iii) **Command Instruction :**

EH	IR	RTS	ER	SBRK	RXE	DTR	TXEN
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(iv) **Status read :**

DSR	SYN/ BRK	FE	OE	PE	TX EMPT	TX RDY	TX RDY
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**2. Programmable interval timer 8253 :**

(i) **Control work format :**

SC <sub>1</sub>	SC <sub>0</sub>	RL <sub>1</sub>	RL <sub>0</sub>	M <sub>2</sub>	M <sub>1</sub>	M <sub>0</sub>	BCD
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(ii) **Mode reg. for latching count :**

SC <sub>1</sub>	SC <sub>0</sub>	0	0	x	x	x	x
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**3. Programmable peripheral interface 8255 :**

(i) **Mode definition :**

MSF	MS <sub>2</sub>	MS <sub>1</sub>	P <sub>A</sub>	P <sub>CU</sub>	MS	P <sub>B</sub>	P <sub>CL</sub>
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P.T.O.

(ii) Bit set reset format :

BSR	×	×	×	BS <sub>2</sub>	BS <sub>1</sub>	BS <sub>0</sub>	BS/R
F							

(iii) Mode 1-input status :

I/O	I/O	IBF	INTE	INTR	INTE	IBF	INTR
A	A	A	A	B	B	B	B

(iv) Mode 1-output status :

OBF	INTE	I/O	I/O	INTR	INTE	OBF	INTR
A	A			A	B	B	B

(v) Mode 2 status :

OBF	INTE	IBF	INTE	INTR	×	×	×
A	1	A	2	A			

Programmable DMA controller 8257 :

(i) Mode set register :

EAL	ETCS	E <sub>EW</sub>	ERP	ECH <sub>3</sub>	ECH <sub>2</sub>	ECH <sub>1</sub>	ECH <sub>0</sub>
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(ii) Count register :

R/W/V	RWV	D <sub>13</sub>	D <sub>12</sub>	....	....	D <sub>1</sub>	D <sub>0</sub>
1	0						

(iii) Status register :

0	0	0	UF	TCS <sub>3</sub>	TCS <sub>2</sub>	TCS <sub>1</sub>	TCS <sub>0</sub>
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5. Programmable interrupt controller 8259 :

(i) ICW<sub>1</sub> :

A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	1	LT1	AD1	BMG <sub>1</sub>	ICW <sub>4</sub>
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(ii) ICW<sub>2</sub> :

A <sub>15</sub>	A <sub>14</sub>	A <sub>13</sub>	A <sub>12</sub>	A <sub>11</sub>	A <sub>10</sub>	A <sub>9</sub>	A <sub>8</sub>
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(iii) ICW<sub>3</sub> (Slave) :

0	0	0	0	0	ID <sub>2</sub>	ID <sub>1</sub>	ID <sub>0</sub>
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(iv) ICW<sub>3</sub> (Master) :

S <sub>7</sub>	S <sub>6</sub>	S <sub>5</sub>	S <sub>4</sub>	S <sub>3</sub>	S <sub>2</sub>	S <sub>1</sub>	S <sub>0</sub>
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(v) ICW<sub>4</sub> :

0	0	0	SFN	BUF	M/S	AE0 <sub>1</sub>	MPM
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(vi) OCW<sub>1</sub> :

M <sub>7</sub>	M <sub>6</sub>	M <sub>5</sub>	M <sub>4</sub>	M <sub>3</sub>	M <sub>2</sub>	M <sub>1</sub>	M <sub>0</sub>
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(vii) OCW<sub>2</sub> :

R	SL	EOI	0	0	L <sub>2</sub>	L <sub>1</sub>	L <sub>0</sub>
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(viii) OCW<sub>3</sub> :

0	ESM M	SMM	0	1	P	RR	RIS
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P.T.O.

nable KBD/Display controller 8279 :  
D/Display Mode Set :

0	0	0	D	D	K	K	K
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(ii) Program clock :

0	0	1	P	P	P	P	P
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(iii) Read FIFO/Sensor RAM :

0	1	0	A <sub>1</sub>	x	A	A	A
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(iv) Read Display RAM :

0	1	1	A <sub>1</sub>	A	A	A	A
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(v) Write Display RAM :

1	0	0	A <sub>1</sub>	A	A	A	A
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(vi) Display write Inhibit/Blanking :

1	0	1	x	IW A	IW B	BL A	BL B
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(vii) Clear :

1	1	0	C <sub>D</sub>	C <sub>D</sub>	C <sub>D</sub>	C <sub>F</sub>	C <sub>A</sub>
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(viii) End Interrupt/Error mode set :

1	1	1	E	x	x	x	x
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(ia) Scanned KBD data format for key code :

CNTL	SHFT	SC <sub>2</sub>	SC <sub>1</sub>	SC <sub>0</sub>	RL <sub>2</sub>	RL <sub>1</sub>	RL <sub>0</sub>
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(x) Sensor matrix data format for key code (switch) :

RL <sub>7</sub>	RL <sub>6</sub>	RL <sub>5</sub>	RL <sub>4</sub>	RL <sub>3</sub>	RL <sub>2</sub>	RL <sub>1</sub>	RL <sub>0</sub>
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