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**CODE NO:- Z-23** 

## FACULTY OF ENGINEERING AND TECHNOLOGY

## B.E(Mechanical) Year Examination - May-2015 Automatic Control System

(Revised)

[Time: Three Hours]

Q.1

[Max. Marks: 80]

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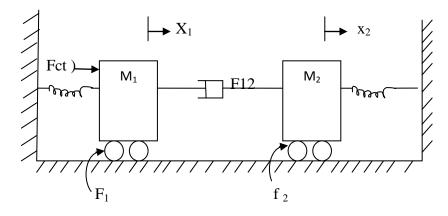
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"Please check whether you have got the right question paper."

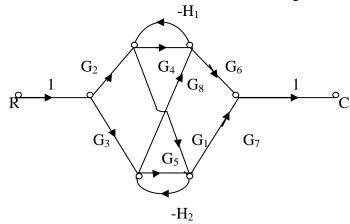
- i) Attempt any three questions from each section.
- ii) Use of semi log and graph paper allowed.
- iii) Make necessary assumptions and state them clearly
- iv) Figures to the right indicate full marks.

## **SECTION - A**

- a) Differentiate open loop and closed loop control system with an example?
- b) Write the differential equations for the mechanical system shown in fig.



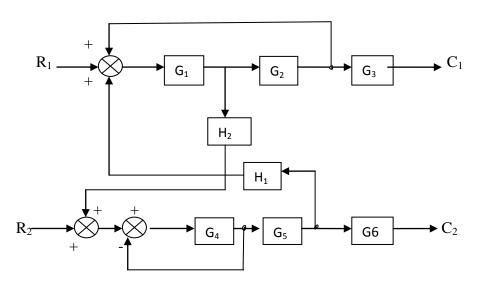
- Q.2 a) Explain in detail fluid system?
  - b) Explain in detail the servomechanism system.
- Q.3 a) Which are the different block reduction rules? Explain in detail.
  - b) Obtain the overall transfer function C/R from signal flow graph shown in fig.



Q.4 a) Explain in detail the derivative and integral type control system.

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b) From the block diagram shown in fig determine  $C_1/R_1$ .



- Q.5 a) Explain in detail position control system.
  - b) Explain in detail PID control system.

## **SECTION - B**

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- Q.6 a) Draw the time response of second order system and define the time response const. for under damped 06 system.
  - b) Find delay time, rise time, peak time settling time, max overshoot for unity feedback system  $G(s) = \frac{16}{s(s+8)}.$
- Q.7 a) For a system G(s).  $H(s) = \frac{k}{s^2(s+2)(s+3)}$  find K to limit the error for input  $1 + 10t + \frac{40}{2}t^2to$  10.
  - b) A unity feedback system characterised by an open loop transfer function  $G(s) = \frac{K}{s(s+10)}$ . Determine the gain K. so that the system will have a damping ratio of 0.5. for this value of K determine settling time, peak overshoot, and time to peak overshoot for unit –step input.
- Q.8 a) Find the range of K for stable operation  $s^4 + 6s^3 + 11s^2 + 6s + k = 0$ 
  - b) Write in detail Nyquist stability criterion. 07
- Q.9 Construct the bode plot for a unity feedback control system having  $G(s) = \frac{4}{s(1+0.5s)(1+0.08s)}$ From the diagram find wgc, wpc, gm, pm and comment on stability.
- Q.10 a) Draw the root locus for the open-loop transfer function  $G(s) = \frac{K}{(s+2)(s+3)(s+7)}$ 
  - b) Explain in detail the method for sketching the root locus

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