SUBJECT CODE:- 301 FACULTY OF ENGINEERING AND TECHNOLOGY B.E.(MECH/PROD) Examination Nov/Dec 2015 Robotics & Industrial Application (OLD)

[Time· T	(OLD)	[Max_Marks: 100]
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	"Please check whether you have got the right question paper." N.B i) Attempt any three questions from each section. ii) Draw neat sketches wherever required. iii) Assume suitable data wherever necessary & state it correctly. Section A	
Q.1	 a) Explain common robot configuration. (five configuration) b) Draw & explain robot construction showing how a robot is made up of a series of joint combinations. 	10 10 Iink 06
Q.2	 a) Explain the following manipulators with two degrees of freedom i) an OO robot ii) an RR robot b) Define work envelope of a robot. 	12 04
Q.3	a) Explain D-H representation. b) Compare drive systems of an industrial robot.	08 08
Q.4	 a) For trajectory planning, what are the general considerations in path description? b) Illustrate the concept of repeatability versus accuracy in reference to robot operation. 	08 08
Q.5	Write short note on the following. i) Robot arm dynamics ii) Robotic joints iii) Scara body & arm assembly.	18
	Section-B	
Q.6	a) Enlist various point to be considered while selecting a sensor. b) Enlist & explain the mechanical grippers.	06 10
Q.7	a) What is the need of vision in a robotic system? How image acquisition is carried out? b) Describe the role of robot in material handling application.	08 08
Q.8	a) Distinguish between magnetic & vacuum grippers. b) Describe program control & data processing in robot language.	08 08
Q.9	a) Explain the application of robot in welding & spray painting.b) Describe type of camera and system interface in vision system	10 06
Q.10	Write short note on the following. i) Artificial intelligence in robotics ii) Robot application in inspection iii) Vision sensors	18